

Simple Harmonic Motion



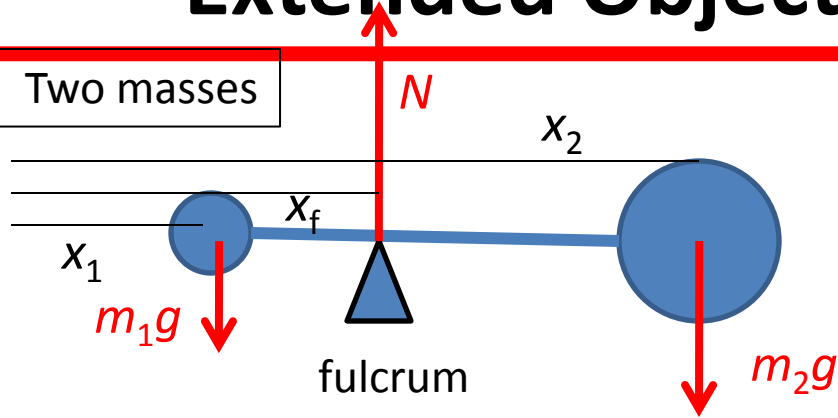
Announcements

- Final exam will be next Wednesday 3:30-5:30
 - A Formula sheet will be provided
 - Closed-notes & closed-books
 - One single-sided 8 ½ X 11 Formula Sheet allowed
 - Bring a calculator
 - Bring your UCD ID (*picture and student number*)
- Practice problems – Online
- Formula sheet – Online
- Review Sessions – Online

Final Exam Room	Last Name Begins With:
198 Young	N - Z
1100 Social Sciences	C - M
55 Roessler	A - B

Extended Objects - Center of Gravity

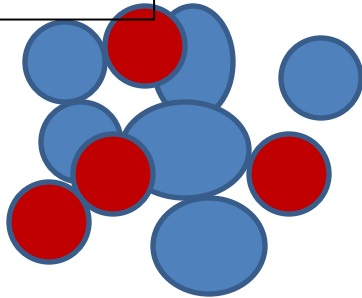
Two masses



Balance forces and Torques

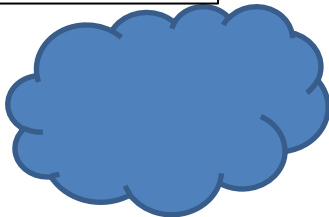
$$x_{cm} = x_f = \frac{m_1x_1 + m_2x_2}{m_1 + m_2}$$

Discrete masses



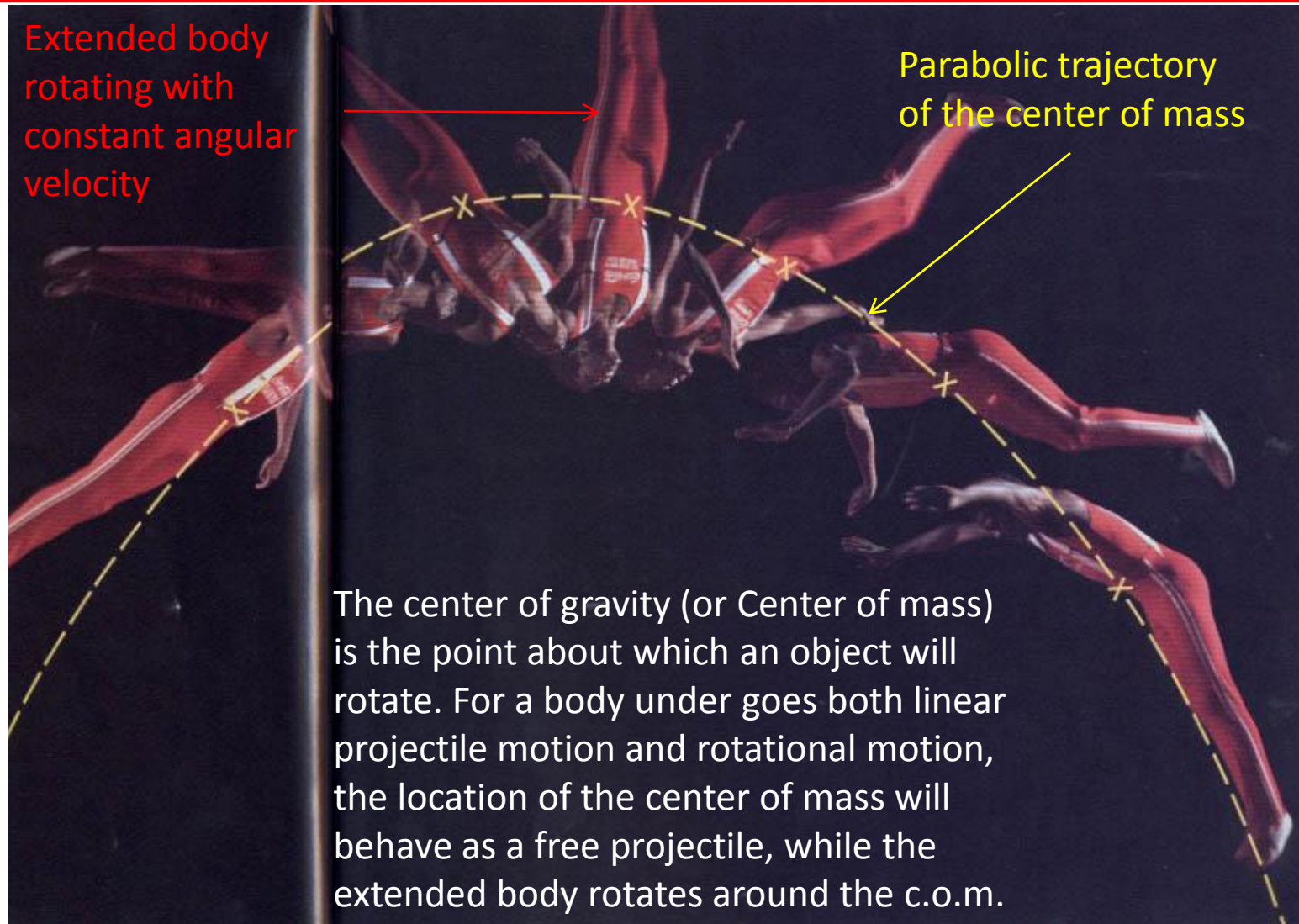
$$x_{cm} = \frac{\sum m_i \vec{r}_i}{\sum m_i}$$

Distribution of mass

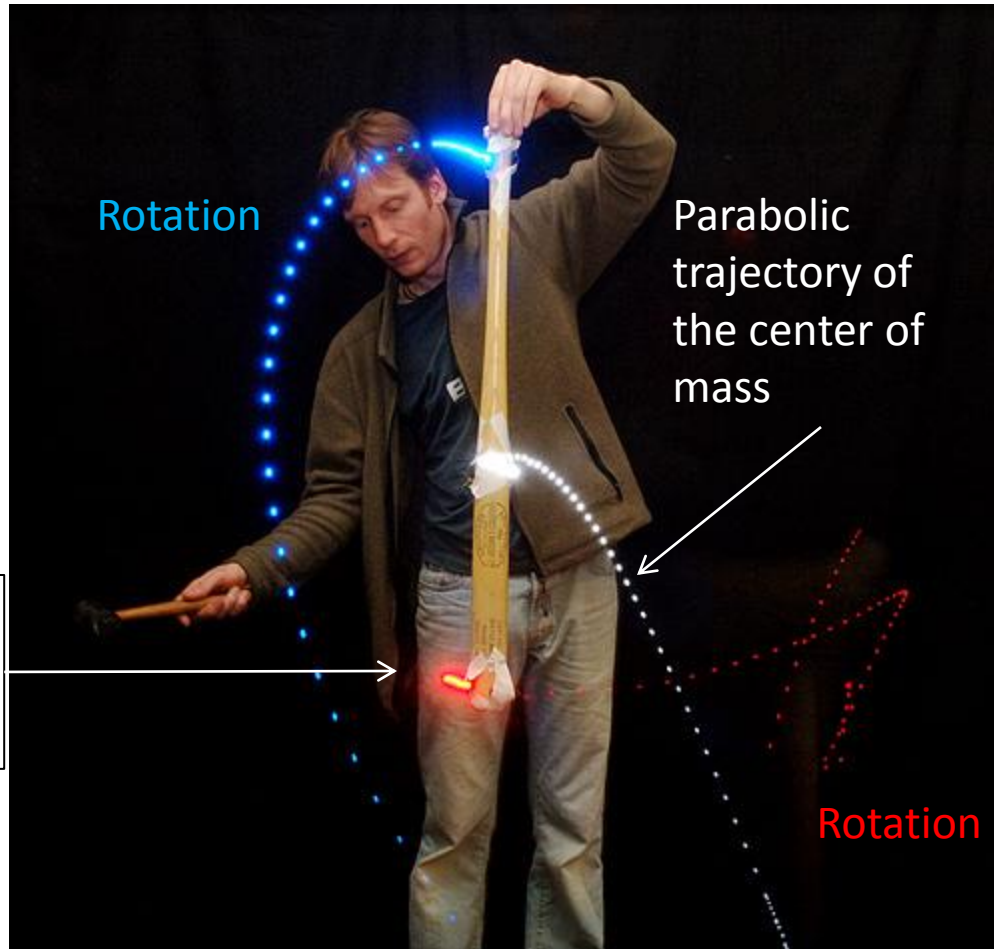


$$x_{cm} = \frac{1}{M} \int \rho(\vec{r}) \vec{r} dV$$

Center of Gravity



Center of Gravity

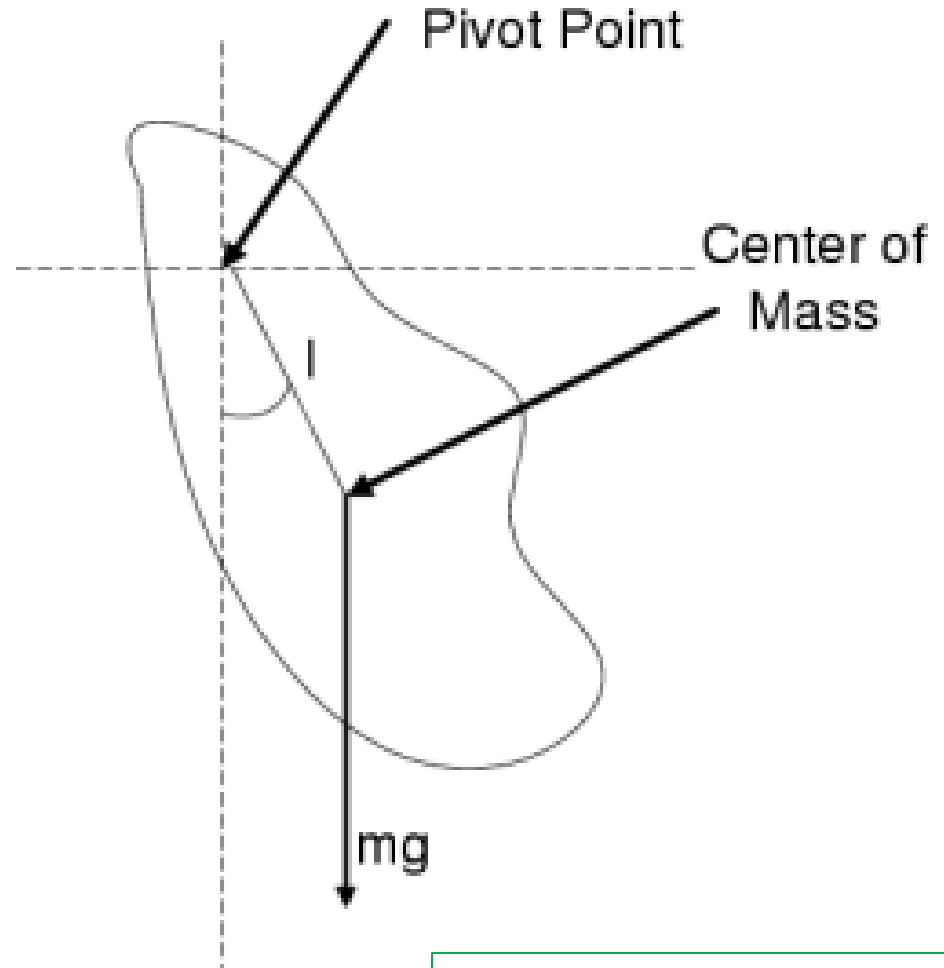


Rotating Off Axis vs On Axis

When can a body rotate about an arbitrary pivot point and when must it rotate about its center of gravity?

First, consider a *free* body (define *free* to mean no contact forces – i.e. Normal forces or frictions). For an object to rotate, there must be Centripetal forces – since these are all *internal* forces, they must add to zero.
→ The body **must** rotate about its center of gravity.

For a body with an *external* fixed pivot point, normal forces at the pivot can provide an *external* centripetal force.



Demo: Center of Gravity

Rotating Off Axis

When rotating off axis, in a uniform gravitational field:

Is the motion circular? → Yes

Is the angular velocity uniform? → No

Is there a net torque? → Yes

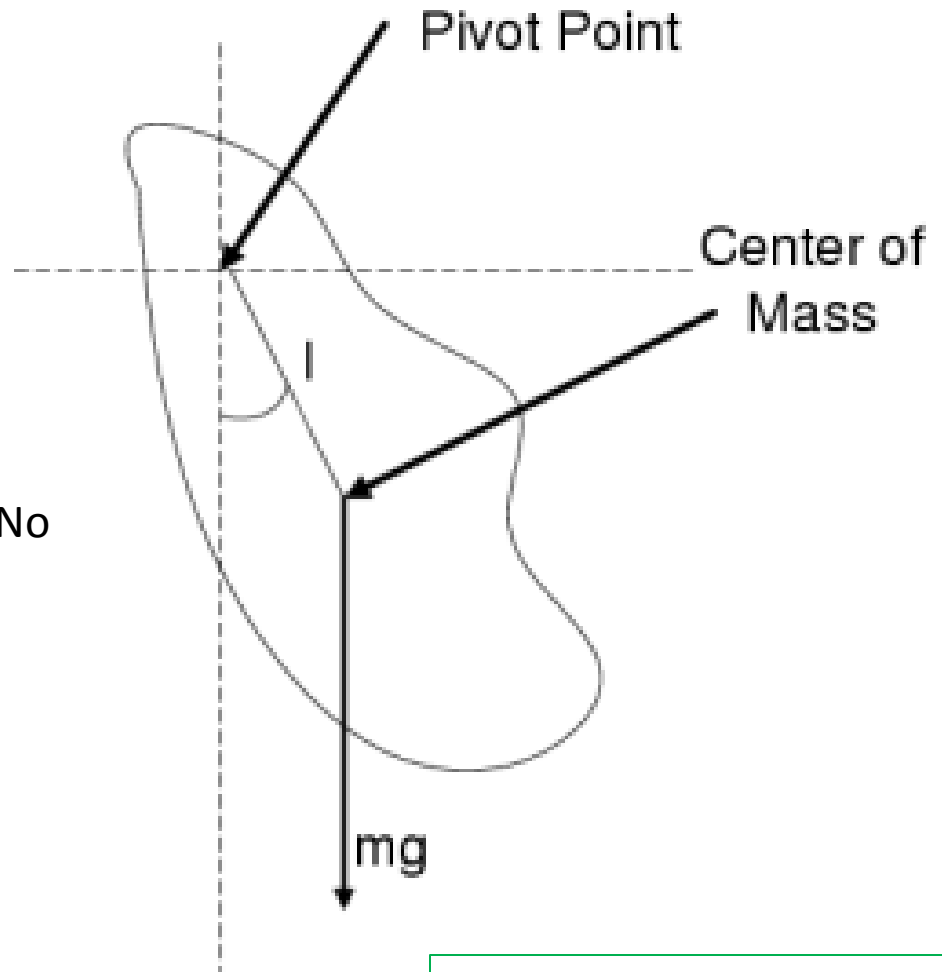
Is the angular acceleration uniform? → No

Is the torque uniform? → No

Is there a net linear motion? → Yes

Is there a net force? → Yes

Is it uniform? → No



Demo: Center of Gravity

Oscillating Off Axis

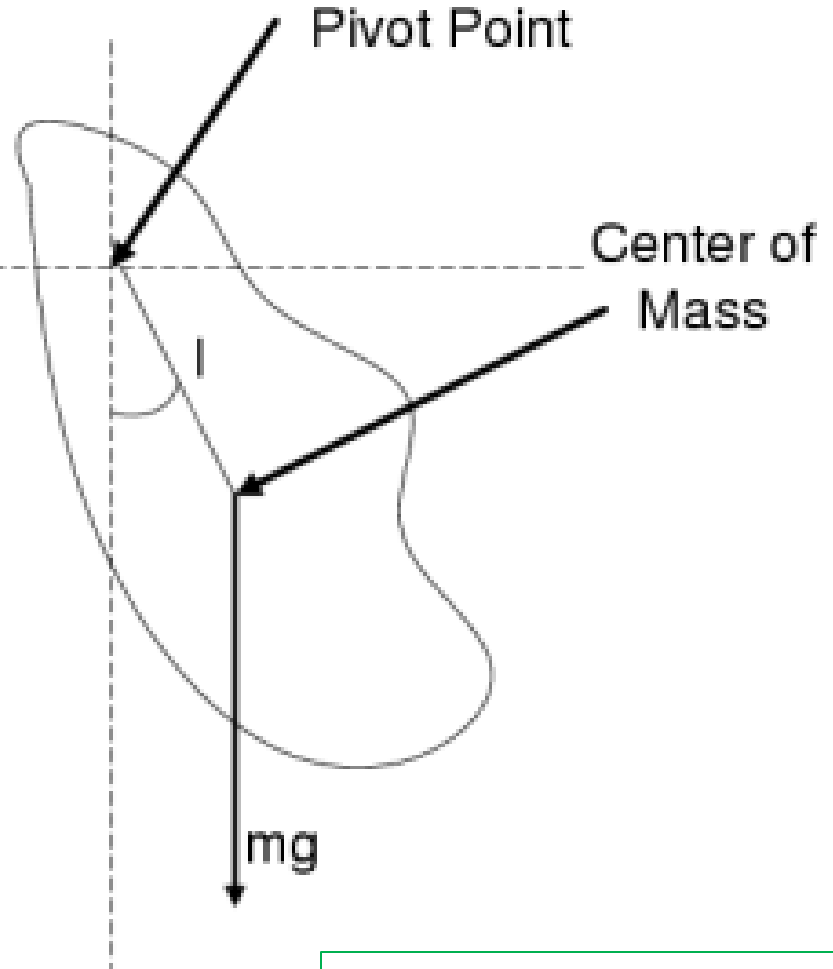
There is an oscillation between kinetic energy ($\frac{1}{2}mv^2$ and $\frac{1}{2}I\omega^2$) and potential energy (mgh).

Where is KE maximum? → The bottom

Where is PE maximum? → The top

What happens if $KE_{\max} < \Delta PE$? → The motion is no longer circular! Instead, the body will oscillate.

Can we describe oscillatory motion?



Demo: Center of Gravity

Oscillatory Motion

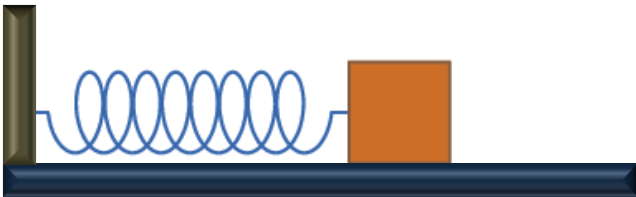
Oscillation: Periodic displacement of an object from an equilibrium point

Periodic or Oscillatory Motion

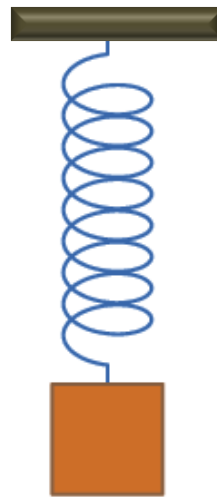
- **Equilibrium Position:** The position at which all forces acting on an object sum to zero.
- **Restoring Force** : Force driving the object towards equilibrium point
 - if restoring force is proportional to displacement => **S.H.M.**
 - i.e. Hooke's Law $\rightarrow F_{\text{restore}} = -kx$
- **Period (T)** : Interval of time for each repetition or cycle of the motion. **Frequency ($f = 1/T$)**
- **Amplitude (A)** : Maximum displacement from equilibrium point
- **Phase (ϕ)**: Describes where in the cycle you are at time $t = 0$.

Examples of Oscillating Systems

*Horizontal
Mass-Spring*



*Vertical
Mass-Spring*

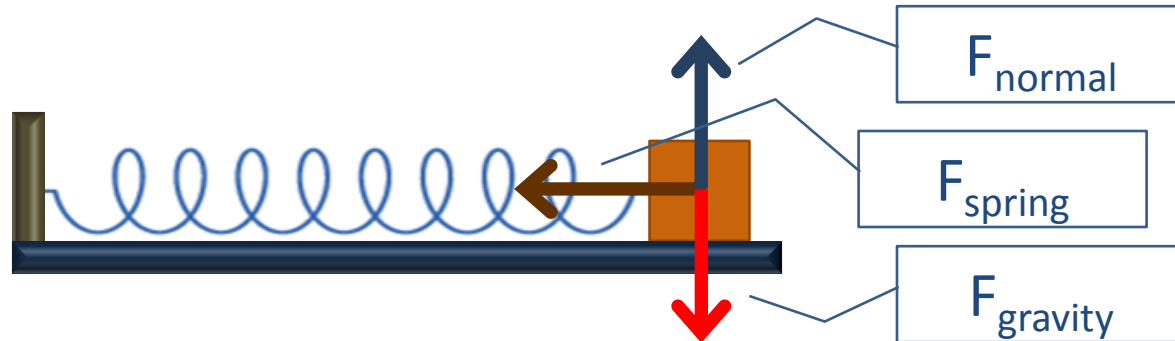


Pendulum

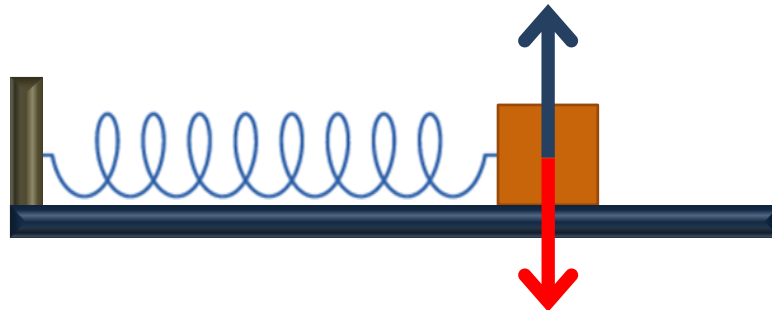


Horizontal Mass-Spring

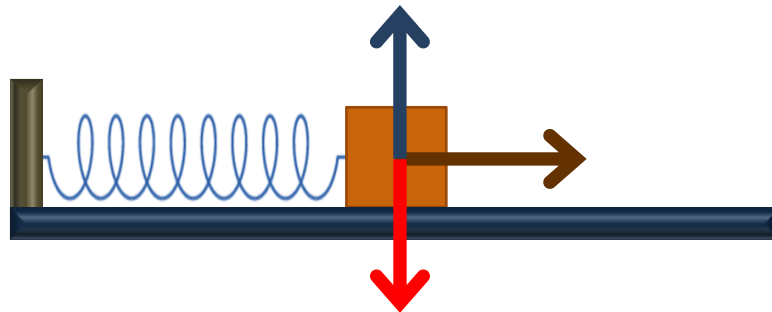
Spring
Extended:



Spring in
Equilibrium:



Spring
Compressed:



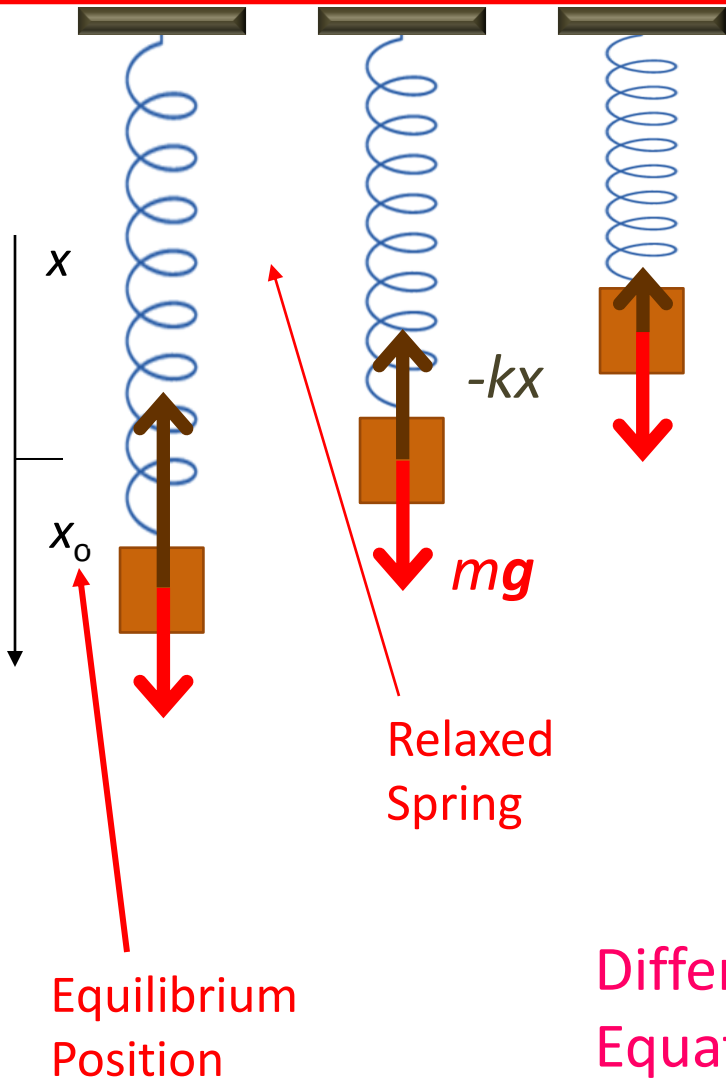
$$F_{\text{gravity}} = -mg$$

$$F_{\text{normal}} = mg$$

$$F_{\text{spring}} = -kx$$

$$F_{\text{Net}} = -kx$$

Vertical Mass on Spring System



Force from a Spring:

$$\mathbf{F}_{\text{spring}} = -k\mathbf{x} \quad (\text{upwards})$$

At Equilibrium:

$$\Sigma \mathbf{F} = -kx_0 + mg = 0$$

Away from Equilibrium:

$$\Sigma \mathbf{F} = -kx + mg = -k(x - x_0) = -kx$$

Newton's 2nd Law ($F=ma$): Let $x = (x - x_0)$

$$\mathbf{F}_{\text{tot}} = -kx(t) = ma(t) = m (d^2x(t)/dt^2)$$

Differential Equation...

DEMO: Spring w/ mass

How to solve this differential equation?

Differential Equation for Simple Harmonic Oscillation

$$\left\{ \begin{array}{l} -kx(t) = m \frac{d^2 x(t)}{dt^2} \\ \frac{d^2 x(t)}{dt^2} = -\frac{k}{m} x(t) \end{array} \right.$$

Do we know any function whose second derivative is itself times a constant?

$$\frac{d}{dt} \sin bt = +b \cos bt$$

$$\frac{d}{dt} \cos bt = -b \sin bt$$

$$\frac{d^2}{dt^2} \sin bt = -b^2 \sin bt$$

$$\frac{d^2}{dt^2} \cos bt = -b^2 \cos bt$$

→ Let

$$x(t) = \sin\left(\sqrt{\frac{k}{m}}t\right)$$

Period:

sine function repeats when

$$bt = 2\pi$$

therefore,

$$T = 2\pi/b$$

$$T = 2\pi \sqrt{m/k}$$

General Solution: $x(t) = A \sin(2\pi t/T + \phi)$ or $x(t) = A \cos(2\pi t/T + \phi)$

Simple Harmonic Motion

- **Simple Harmonic Motion:** Oscillatory motion in which the restoring force is proportional to displacement

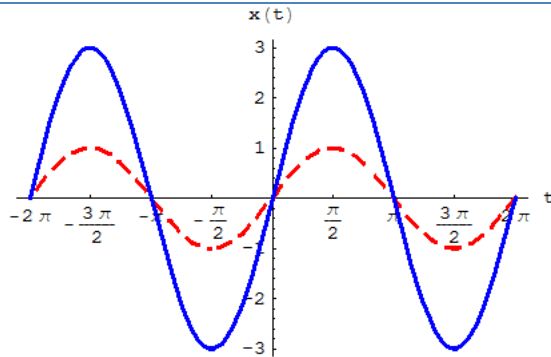
Restoring Force = Constant \times Displacement

- Displacement vs. Time:

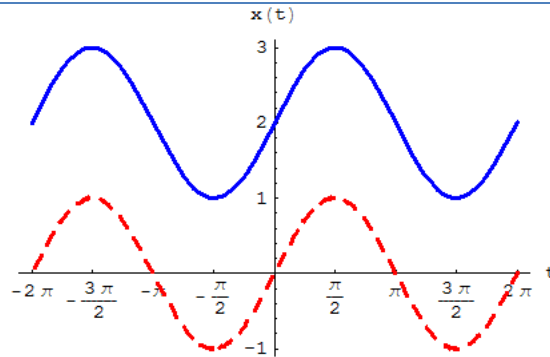
$$x(t) = A \sin\left(\frac{2\pi}{T} t + \phi\right) + B$$

Practice With SHM Equation

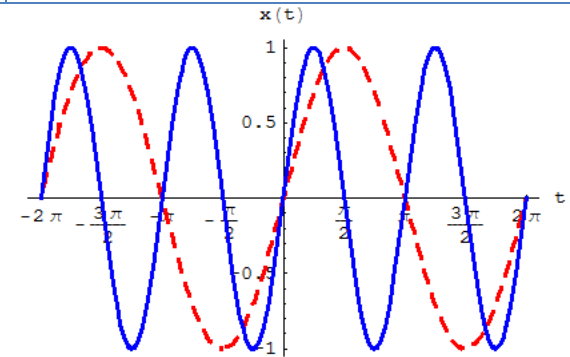
$\sin(t) \quad , \quad 3 \sin(t)$



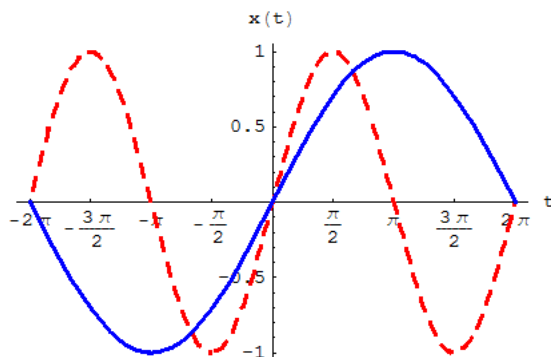
$\sin(t) \quad , \quad \sin(t)+2$



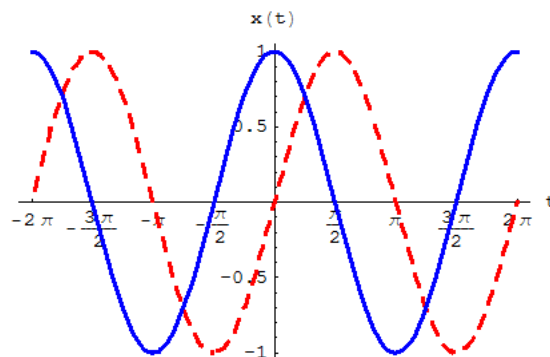
$\sin(t) \quad , \quad \sin(2t)$



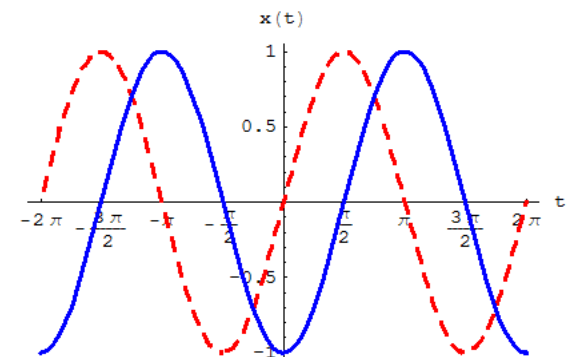
$\sin(t) \quad , \quad \sin(0.5 t)$



$\sin(t) \quad , \quad \sin(t + 0.5 \pi)$

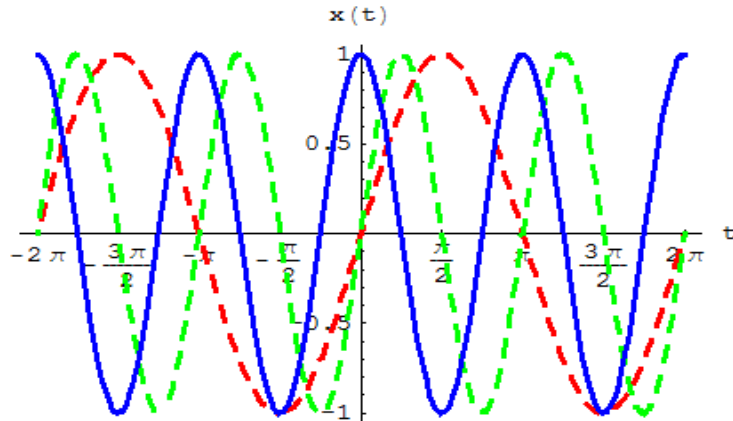


$\sin(t) \quad , \quad \sin(t - 0.5 \pi)$

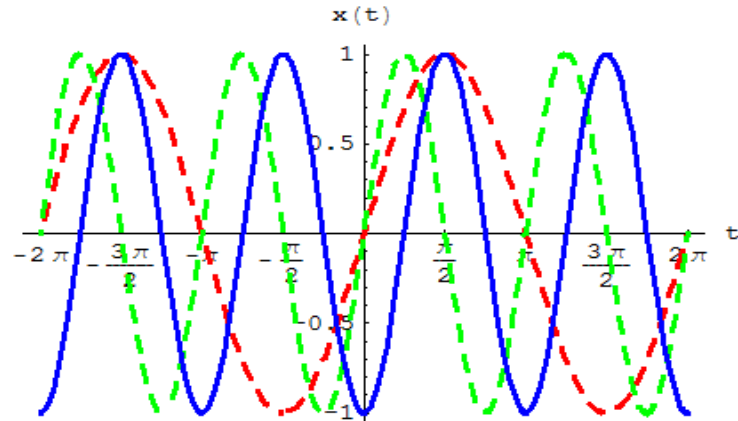


Practice With SHM Equation

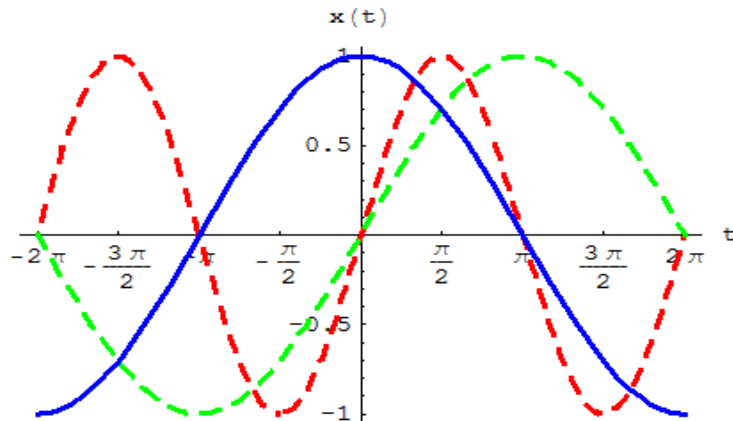
$$\sin(t), \sin(2t), \sin(2t+0.5\pi)$$



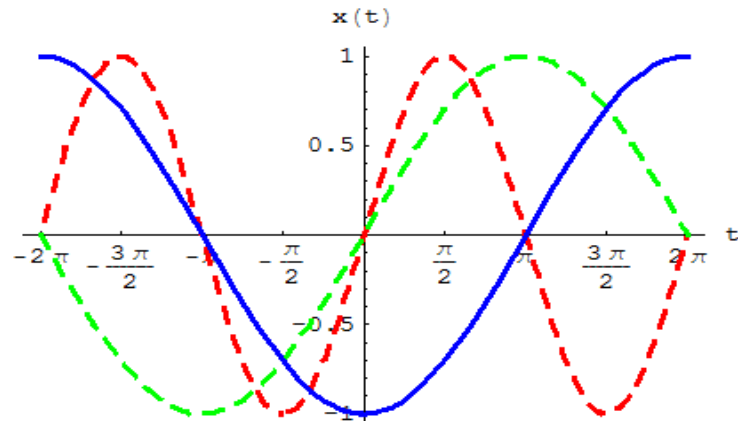
$$\sin(t), \sin(2t), \sin(2t-0.5\pi)$$



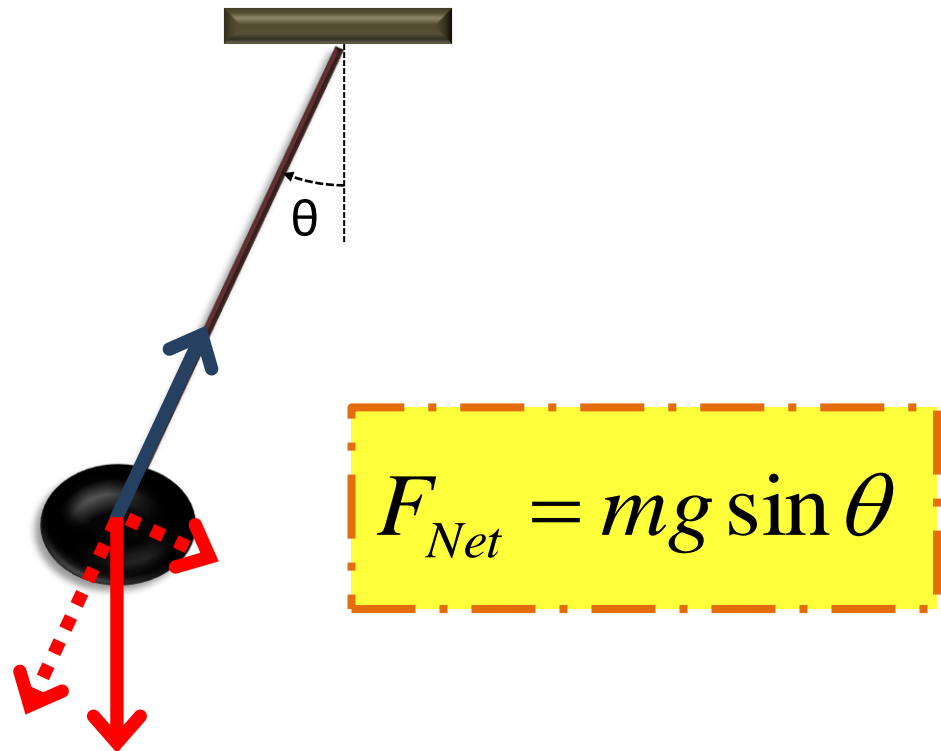
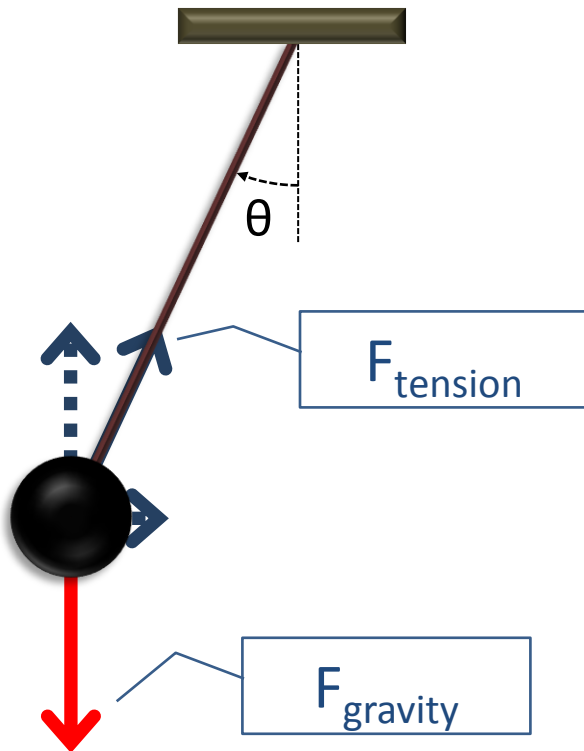
$$\sin(t), \sin(0.5t), \sin(0.5t+0.5\pi)$$



$$\sin(t), \sin(0.5t), \sin(0.5t-0.5\pi)$$



Pendulum System



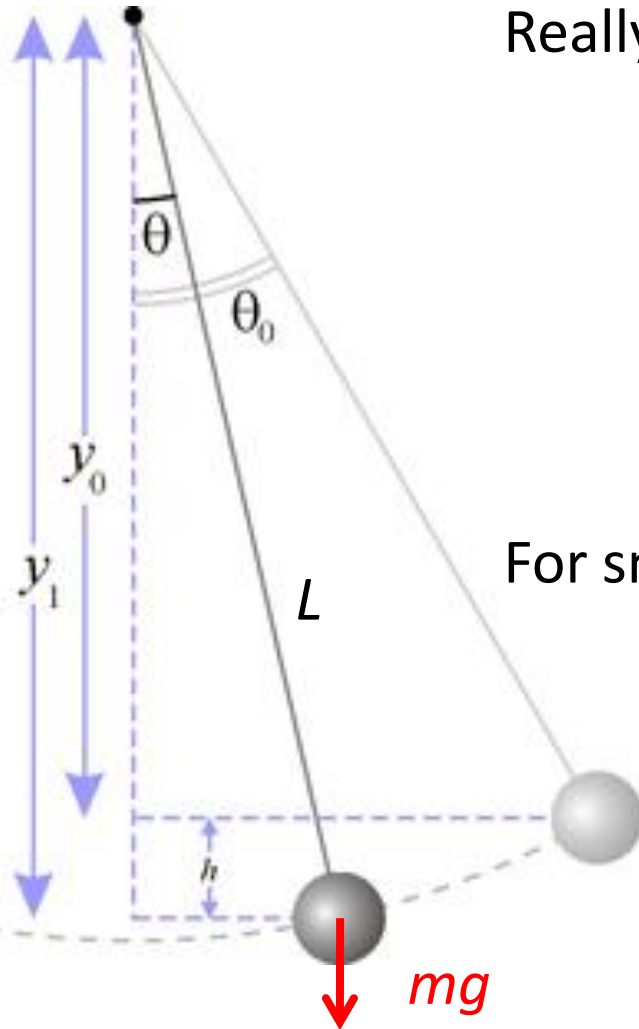
$$F_{tensionX} = F_{tension} \sin \theta$$

$$F_{tensionY} = F_{tension} \cos \theta$$

$$F_{gravityT} = F_{gravity} \sin \theta = mg \sin \theta$$

$$F_{gravityR} = F_{gravity} \cos \theta = mg \cos \theta$$

Pendulum System



Really a rotational problem...

$$\tau = F_{\tan} L = mg \sin \theta L$$

$$\tau = I \alpha = mL^2 \alpha$$

$$-mgL \sin \theta = mL^2 d^2\theta/dt^2$$

For small θ , $\sin \theta = \theta$ (good to about 10 degrees)

$$-mgL\theta(t) = mL^2 d^2\theta/dt^2$$

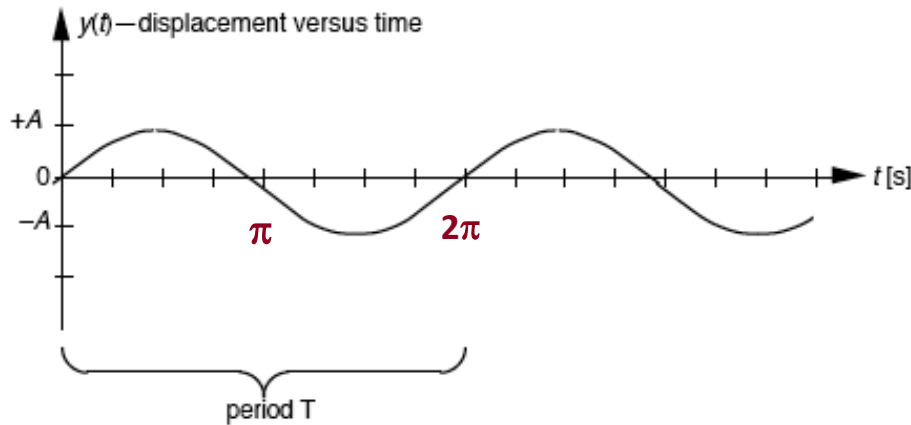
$$-(g/L)\theta(t) = d^2\theta/dt^2$$

$$T = 2\pi \sqrt{L/g}$$

SHM - Recap

The generalized solution is of the form:

$$y(t) = A \sin\left(\frac{2\pi}{T} t + \phi\right) + B$$



Pendulum: $T = 2\pi \sqrt{\frac{l}{g}}$

Mass/Spring: $T = 2\pi \sqrt{\frac{m}{k}}$

How is the frequency f of the oscillations related to the period T ?

Period: $T = \frac{1}{f} = \frac{1}{1/\text{sec}} = \text{sec}$

Energy in SHM

Consider mass on a spring:

$$W = \int F \cdot dl = \int kx dx = \frac{1}{2} kx^2$$

$$PE = (1/2) k x^2$$

$$KE = (1/2) m v^2 \quad v = dx/dt$$

$$x(t) = A \sin(2\pi t/T + \phi)$$

$$PE = (1/2) k A^2 \sin^2 (2\pi t/T + \phi)$$

$$KE = (1/2) m [(2\pi/T) A \cos(2\pi t/T + \phi)]^2$$

remember... $(2\pi/T) = \text{sqrt}(k/m) \Rightarrow (2\pi/T)^2 = k/m$

$$\Rightarrow KE = (1/2) A^2 k \cos^2 (2\pi t/T + \phi)$$

$$E_{\text{total}} = PE + KE = (1/2) k A^2 [\sin^2 (2\pi t/T + \phi) + \cos^2 (2\pi t/T + \phi)]$$

$$KE_{\text{peak}} = PE_{\text{peak}}$$

→ Energy is conserved with time!
And Energy is proportional to A^2

1

Topics (1/4)

- Fluids
 - Continuity Eq.
 - Energy Density Eq.
 - Steady-state Flow
 - Flow Line
 - Pressure
- Electrical Circuits
 - Batteries
 - Resistors
 - Capacitors
 - Power
 - Voltage
 - Current
 - Equivalent Circuits
- Linear Transport Model
 - Linear Transport Eq.
 - Current Density
 - Exponentials

Topics (2/4)

- Vectors
 - Addition
 - Subtraction
 - Cartesian Coords.
 - Polar Coords.
- Position Vector
- Velocity Vector
- Acceleration Vector
- Momentum Vector
 - Conservation of Momentum
- Force Vector
 - Friction
 - Normal
 - Gravity
 - Spring

Topics (3/4)

- Newton's Laws
 - Force & Acceleration
 - Force & Momentum
 - Ang. Acceleration
 - Ang. Momentum
 - Torque
- Collisions
 - Momentum Cons.
 - Elastic vs. Inelastic
- Rotational Motion
 - Ang. Velocity
- Right Hand Rule
- Conservation of Ang. Momentum
- Moment of Inertia
 - Rotational Kin. Energy

Topics (4/4)

- Oscillations
 - Period
 - Amplitude
 - Mass-spring system
 - Pendulum
 - Simple Harmonic Motion
 - Phase Constant

Evaluations

Practice With SHM Equation

--- $\sin(t)$

--- $\sin(t - \frac{\pi}{2})$

— $\sin(\frac{1}{2}t - \frac{\pi}{2})$

--- $\sin(\frac{1}{2}t)$

